

Data Analysis and Visualization

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Here's the plan...

- **Examples of visualizations**
- **Visualization resources**
- **Visualization tools and formats**
- **Data representations**
- **Visualization for debugging**
- **In Situ Visualization and Analysis**

Multi-Scale Simulation / Visualization

Arterial Blood Flow

Data courtesy of:
George Karniadakis
and Leopold Grinberg,
Brown University

Anterior Cerebral

Middle
Cerebral

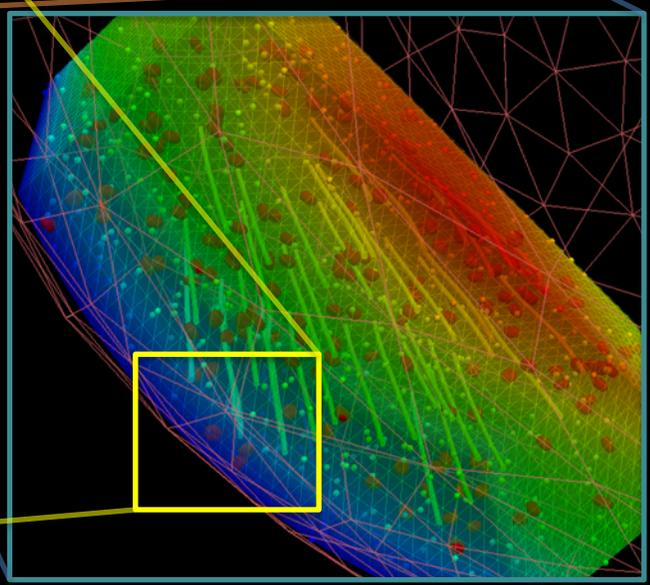
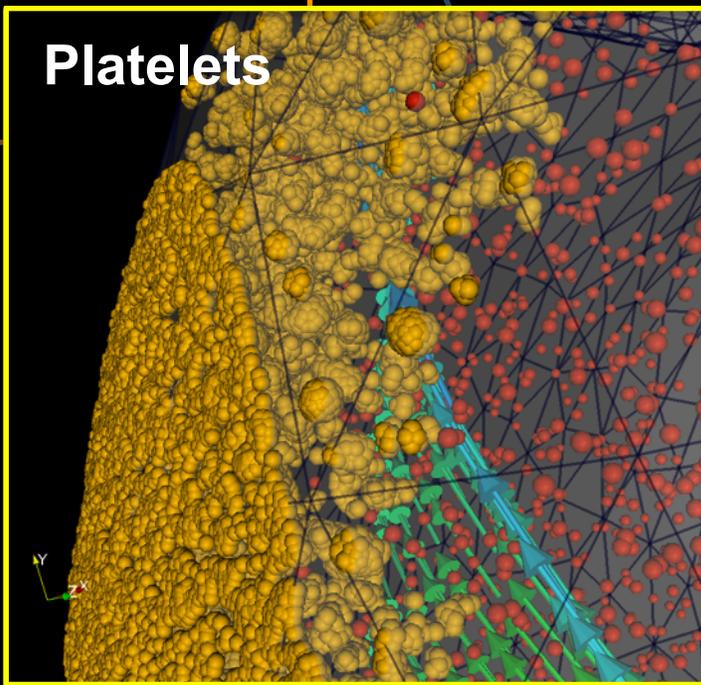
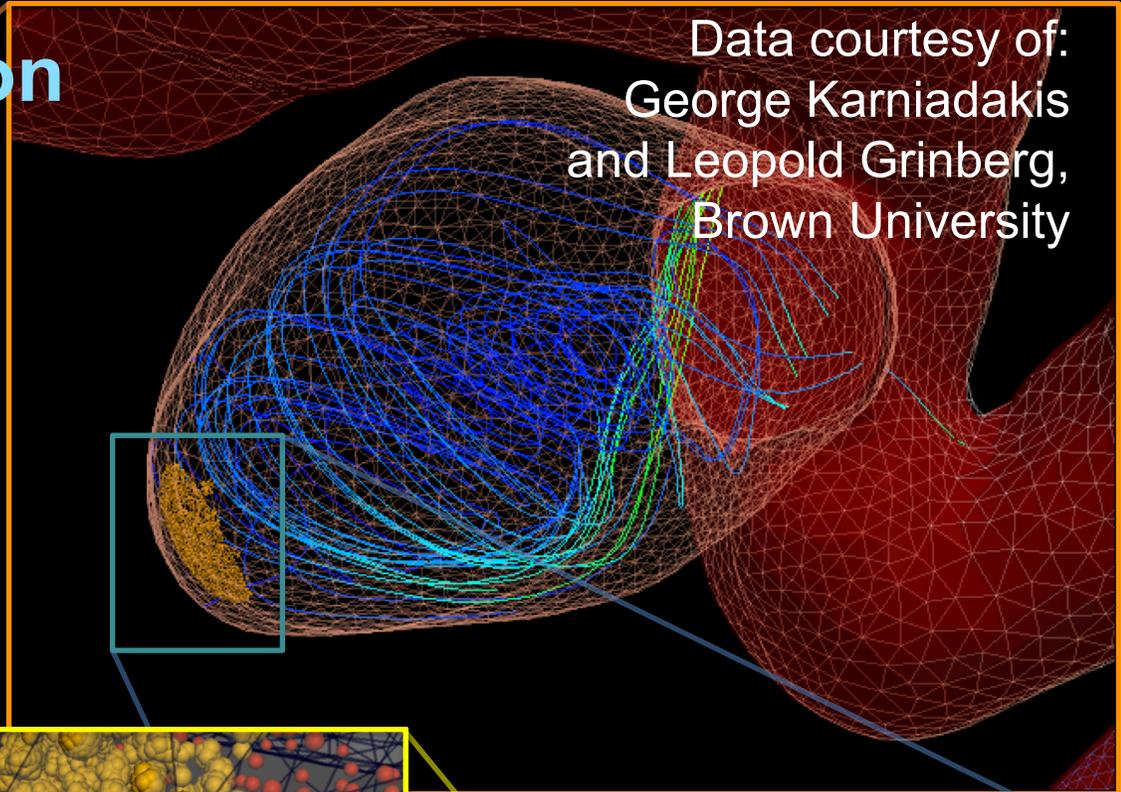
Aneurysm

Right Interior
Carotid Artery

Basilar

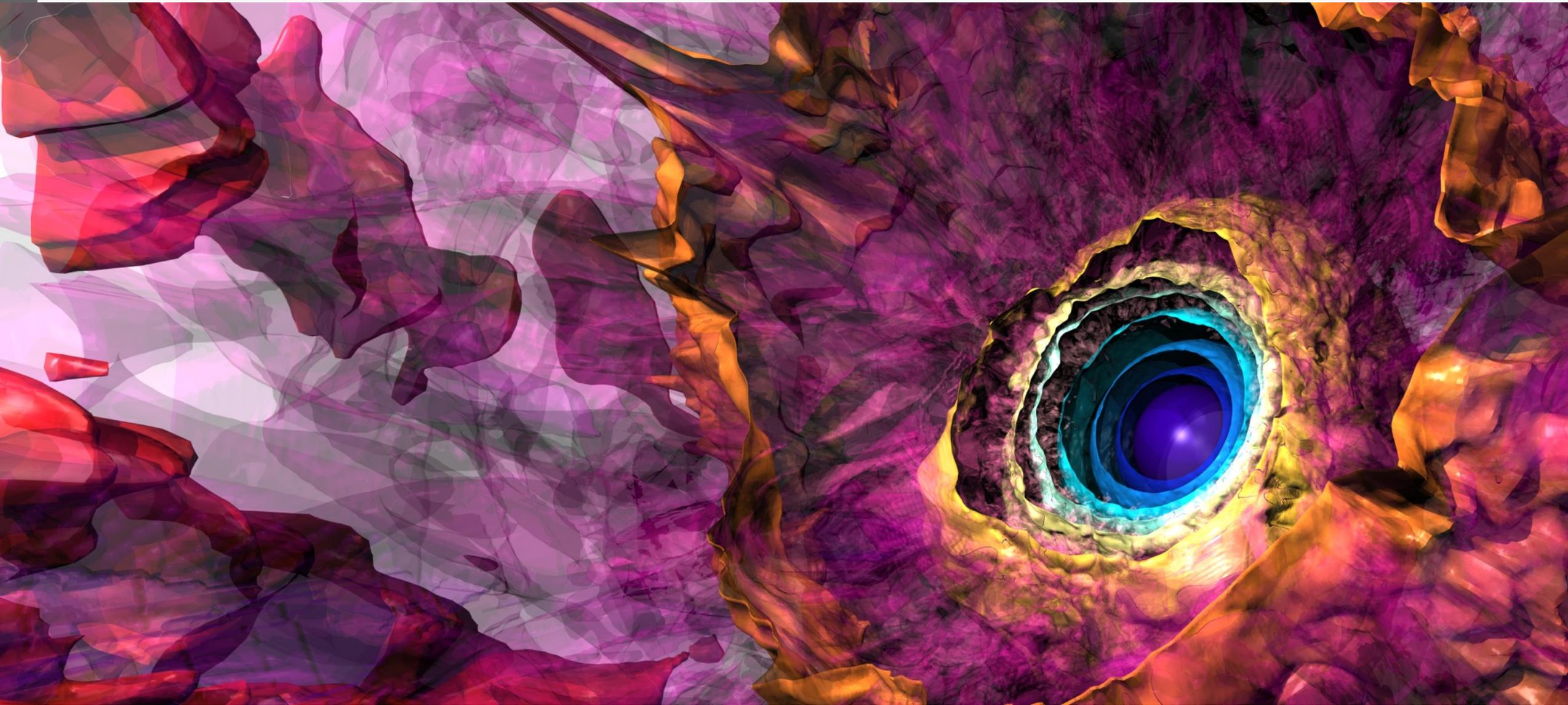
Left Interior
Carotid
Artery

Vertebral

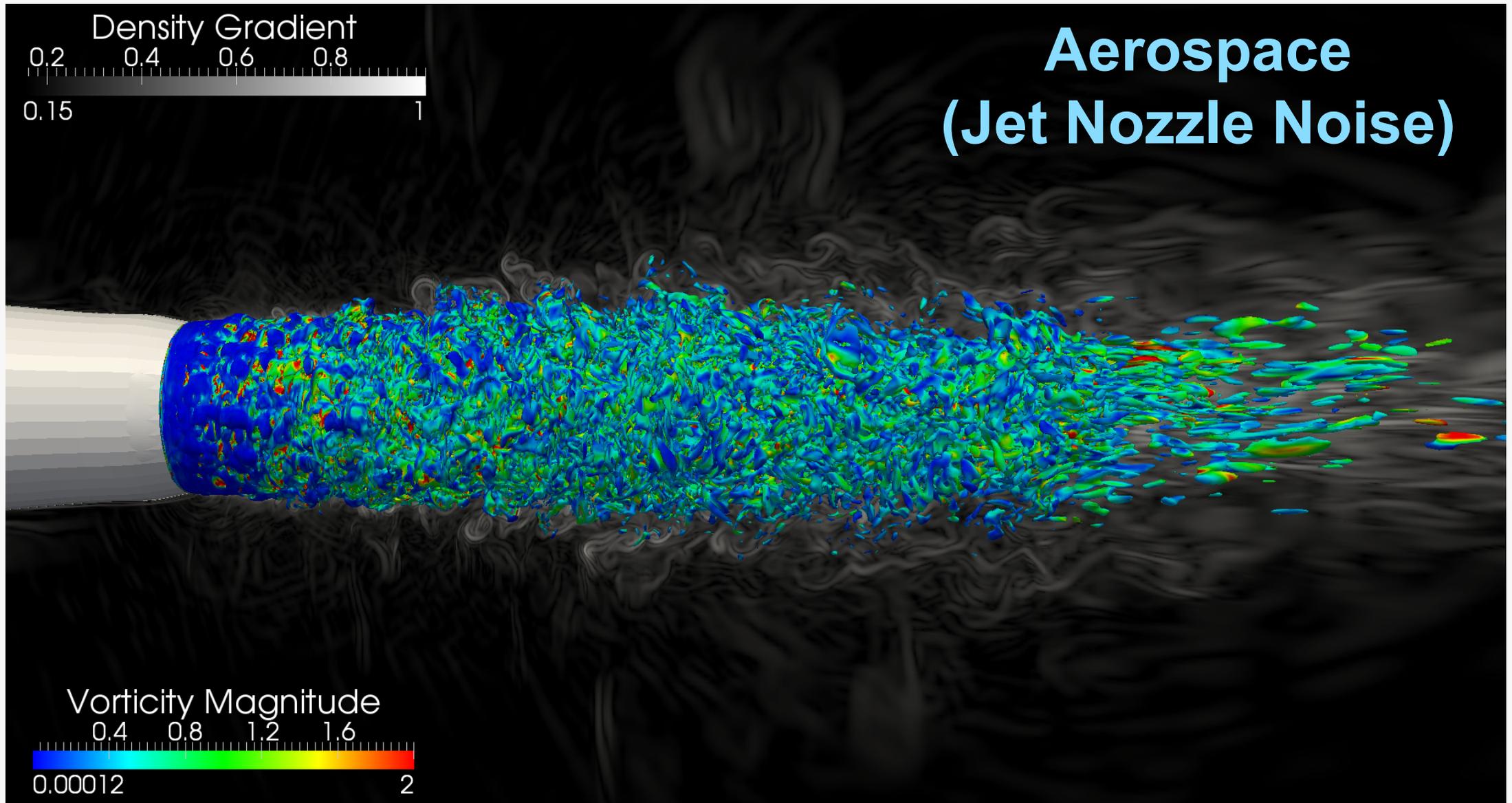


Physics

Data courtesy of: Lars Bildsten and Yan-Fei Jiang, University of California at Santa Barbara

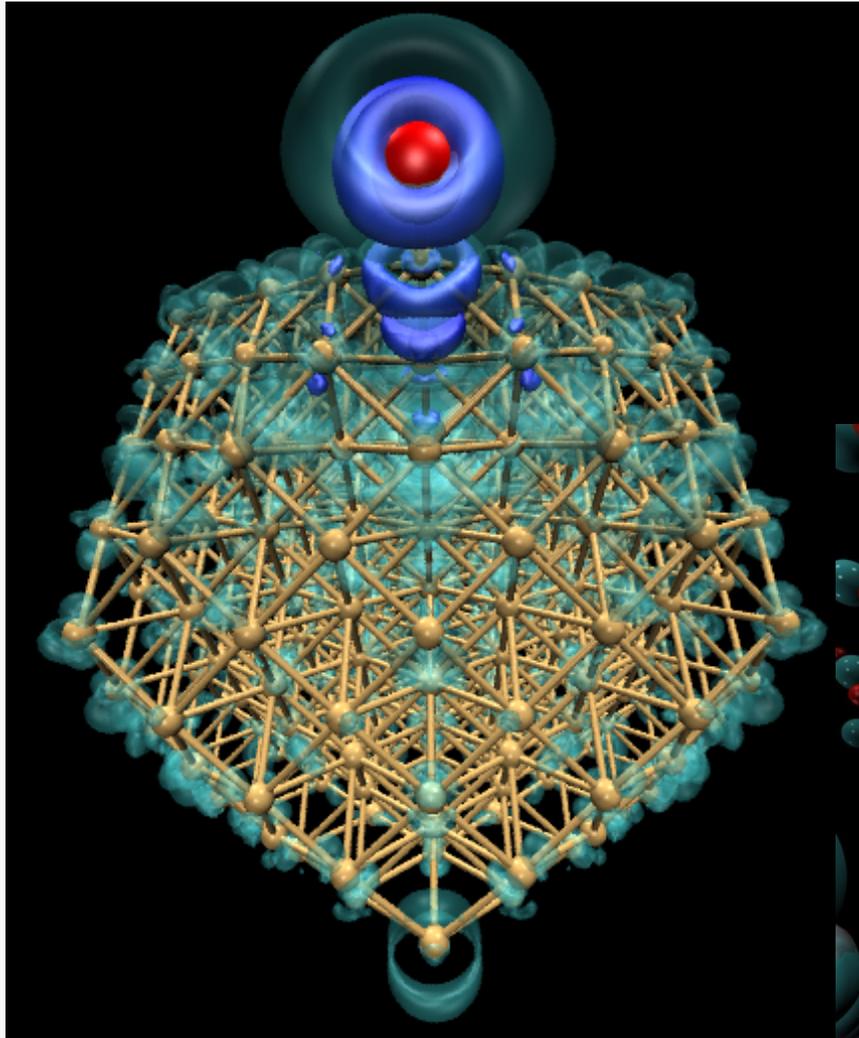


Aerospace (Jet Nozzle Noise)



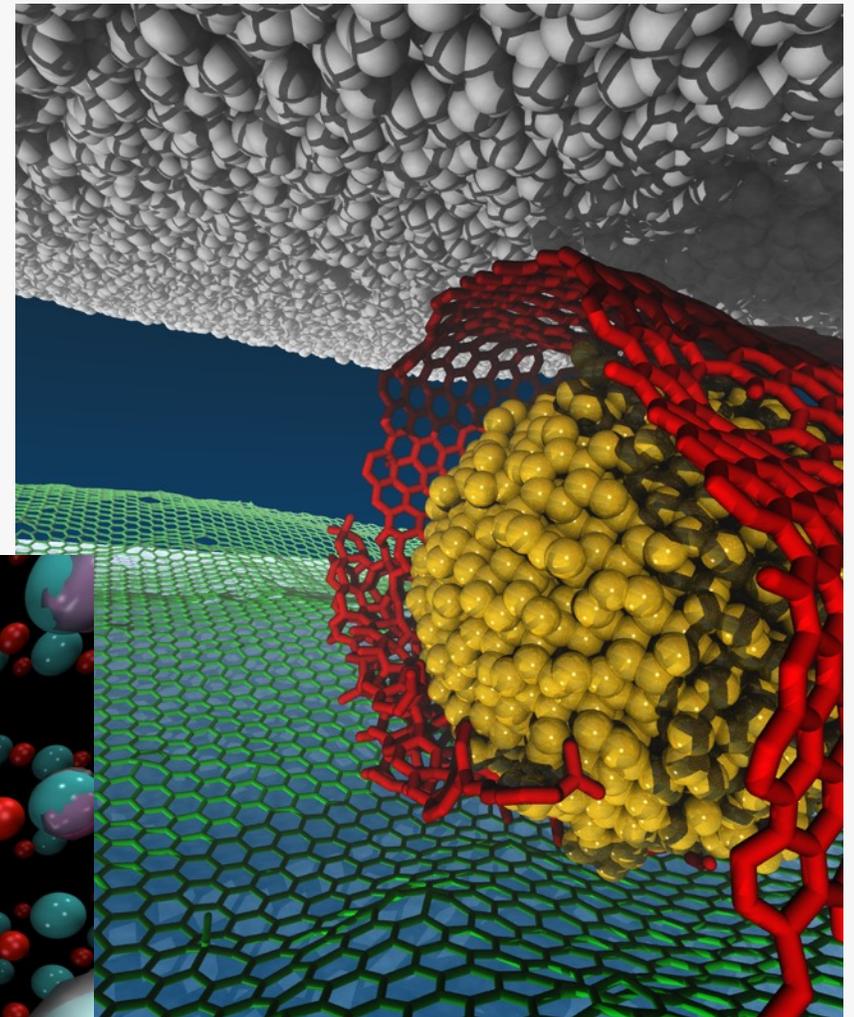
Data courtesy of: Anurag Gupta and Umesh Paliath, General Electric Global Research

Materials Science / Molecular

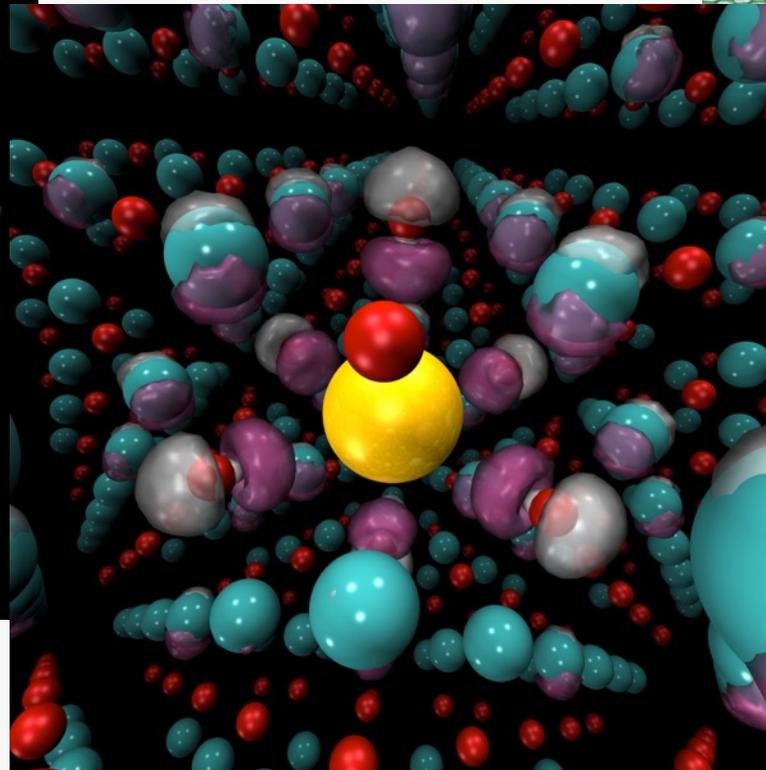


Data courtesy of: Jeff Greeley, Nichols Romero, Argonne National Laboratory

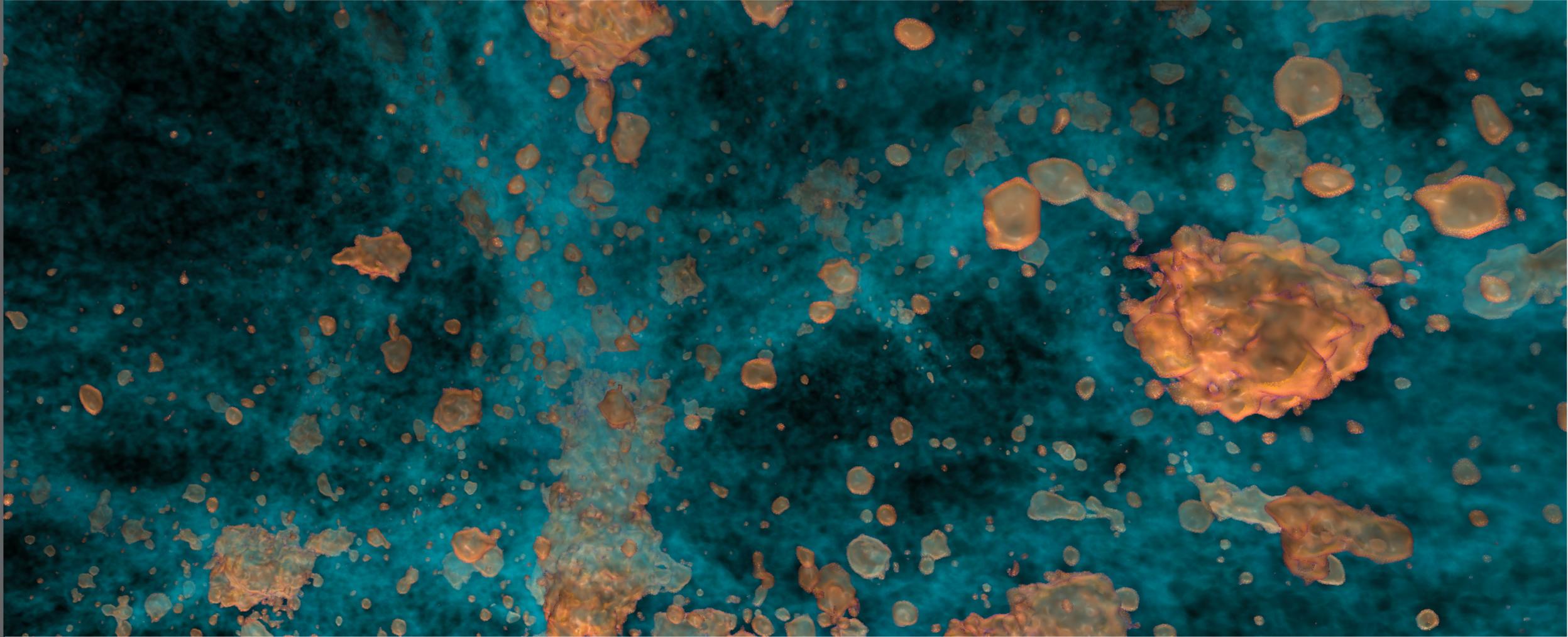
Data courtesy of:
Subramanian
Sankaranarayanan,
Argonne National
Laboratory



Data courtesy of: Paul Kent, Oak Ridge National Laboratory, Anouar Benali, Argonne National Laboratory



Cosmology



Data courtesy of: Salman Habib, Katrin Heitmann, and the HACC team, Argonne National Laboratory

Cooley: Analytics/Visualization cluster

Peak 223 TF

126 nodes; each node has

- Two Intel Xeon E5-2620 Haswell 2.4 GHz 6-core processors
- NVIDIA Telsa K80 graphics processing unit (24GB)
- 384 GB of RAM

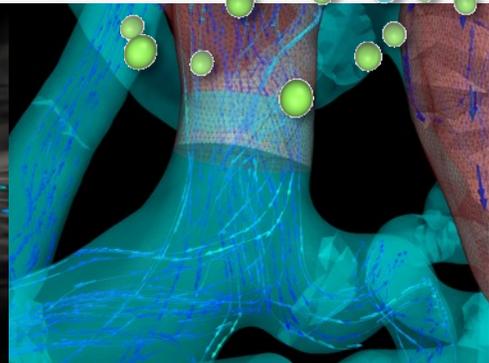
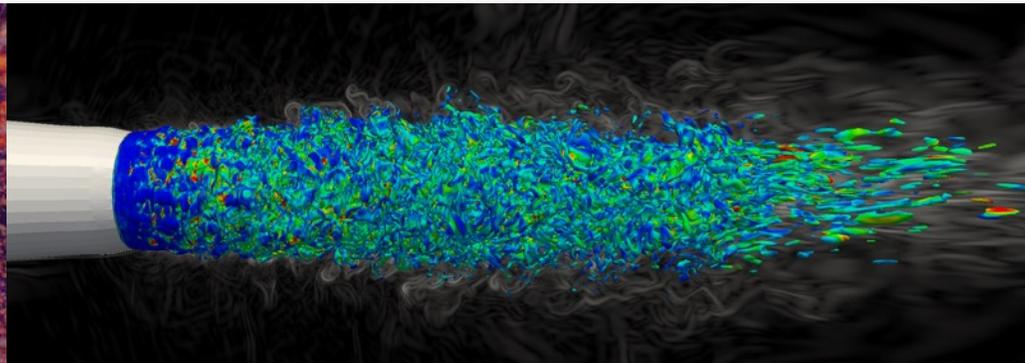
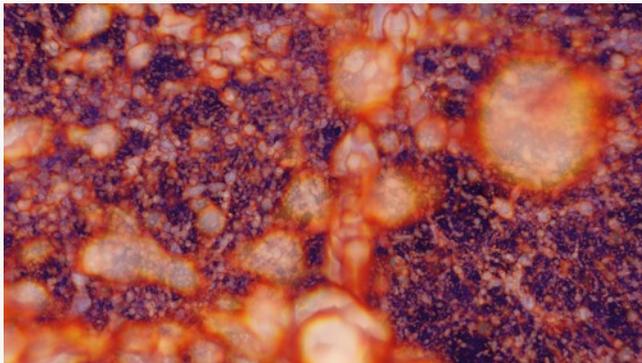
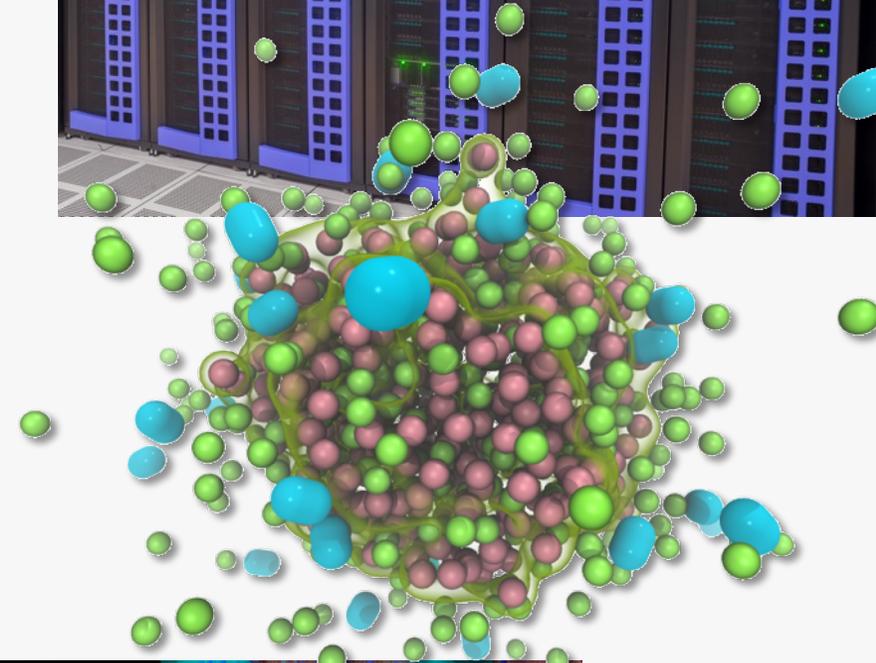
Aggregate RAM of 47 TB

Aggregate GPU memory of ~3TB

Cray CS System

216 port FDR IB switch with uplinks to our QDR infrastructure

Mounts the Theta file system





Visualization Tools and Data Formats

All Sorts of Tools

Visualization Applications

- **VisIt** *
- **ParaView** *
- EnSight

Domain Specific

- **VMD**, PyMol, **Ovito**

APIs

- **VTK** *: visualization
- ITK: segmentation & registration

GPU performance

- **vl3**: shader-based volume and particle rendering

Analysis Environments

- **Matlab**
- Parallel R

Utilities

- **GnuPlot**
- **ImageMagick** *

■ Available on Cooley

* Available on Theta

ParaView & VisIt vs. vtk

ParaView & VisIt

- General purpose visualization applications
- GUI-based
- Client / Server model to support remote visualization
- Scriptable / Extendable
- Built on top of vtk (largely)
- *In situ* capabilities



vtk

- Programming environment / API
- Additional capabilities, finer control
- Smaller memory footprint
- Requires more expertise (build custom applications)

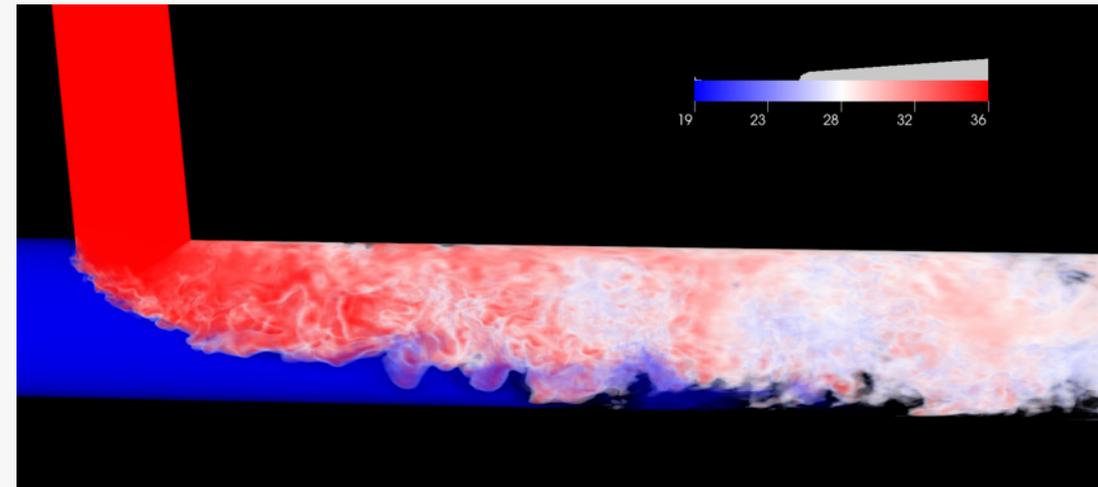
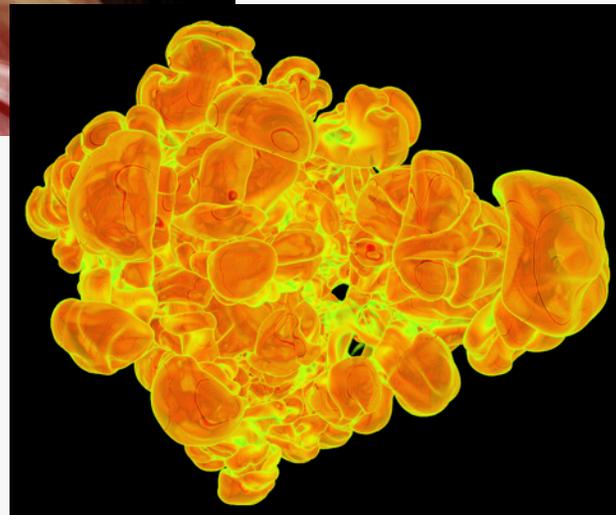
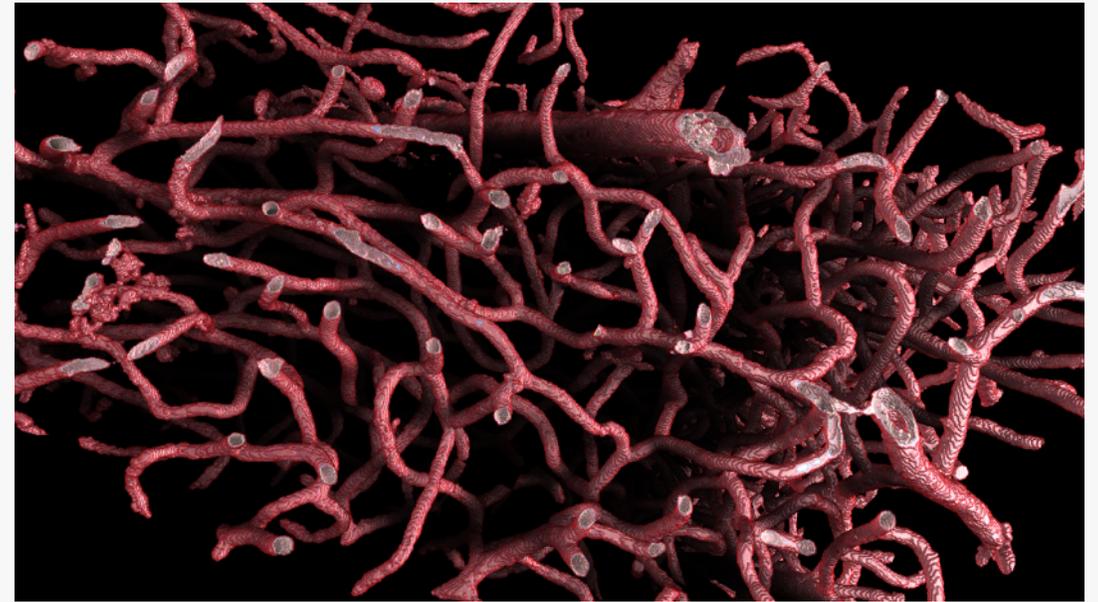
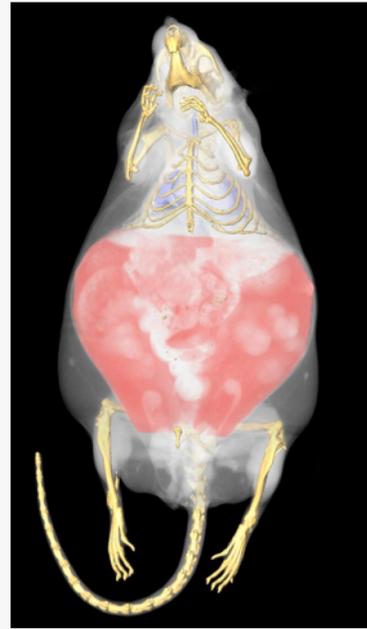
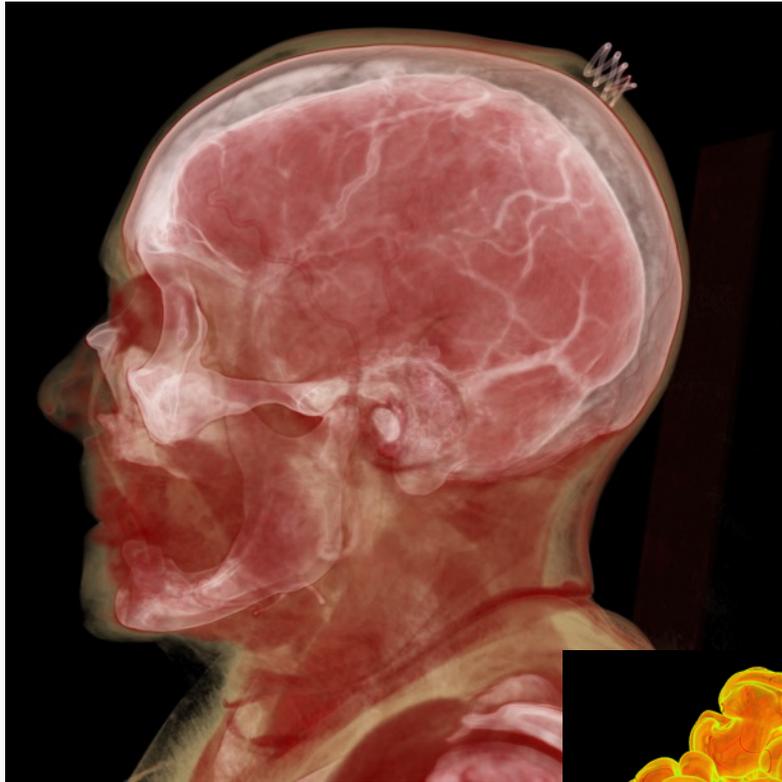


Data File Formats (ParaView & VisIt)

| | | | |
|---|--------------------------------|----------|---------|
| VTK | PLOT3D | Facet | Tetrad |
| Parallel (partitioned) VTK | SpyPlot CTH | PNG | UNIC |
| VTK MultiBlock (MultiGroup, Hierarchical, Hierarchical Box) | HDF5 raw image data DEM | SAF | VASP |
| Legacy VTK | VRML | LS-Dyna | ZeusMP |
| Parallel (partitioned) legacy VTK | PLY | Nek5000 | ANALYZE |
| EnSight files | Polygonal Protein Data Bank | OVERFLOW | BOV |
| EnSight Master Server | XMol Molecule | paraDIS | GMV |
| Exodus | Stereo Lithography | PATRAN | Tecplot |
| BYU | Gaussian Cube | PFLOTRAN | Vis5D |
| XDMF | Raw (binary) | Pixie | Xmdv |
| PLOT2D | AVS | PuReMD | XSF |
| | Meta Image | S3D | |
| | | SAS | |

Data Representations

Data Representations: Volume Rendering



Data Representations: Glyphs

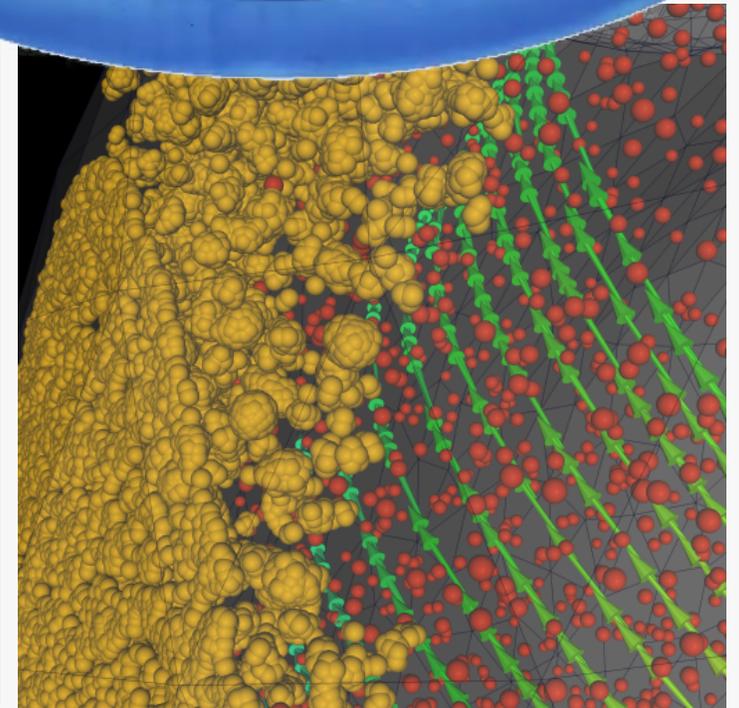
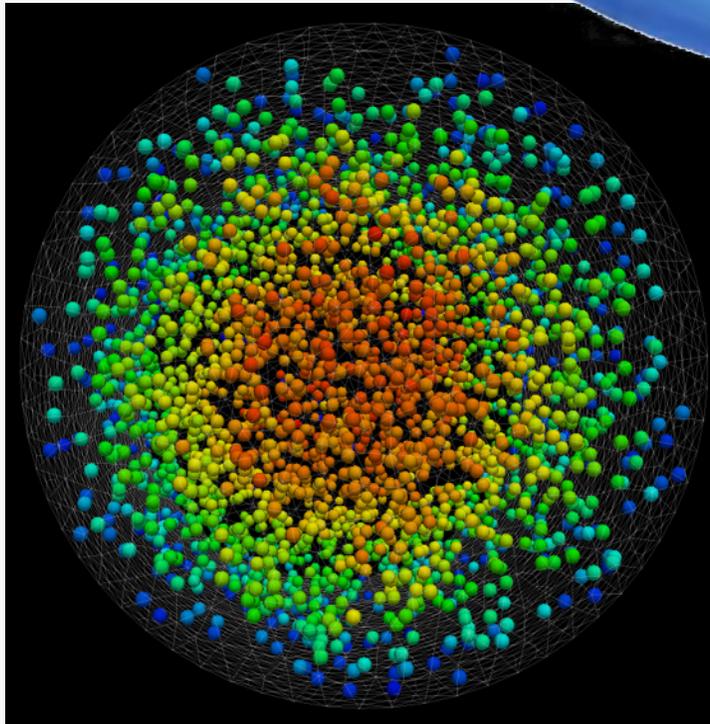
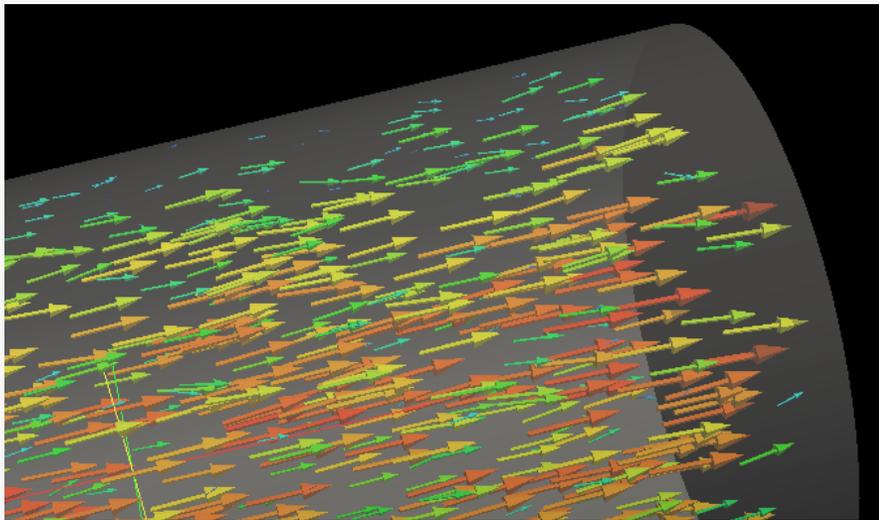
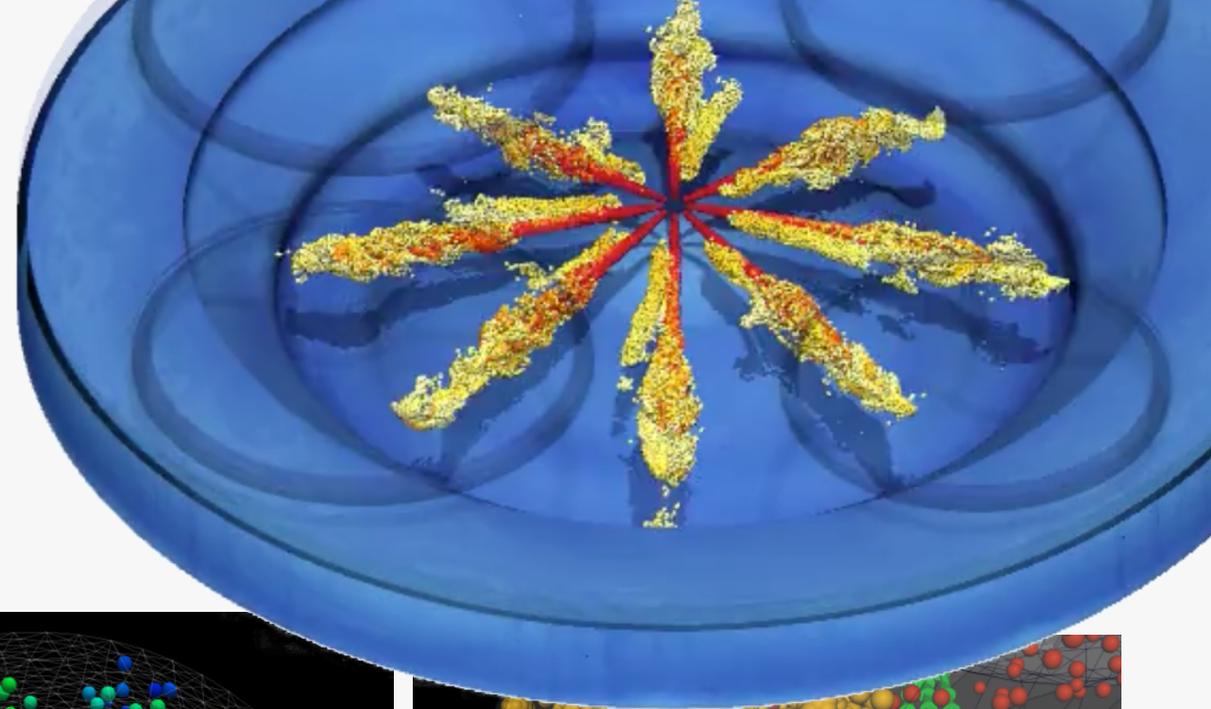
2D or 3D geometric object to represent point data

Location dictated by coordinate

- 3D location on mesh
- 2D position in table/graph

Attributes of graphical entity dictated by attributes of data

- color, size, orientation



Data Representations: Contours (Isosurfaces)

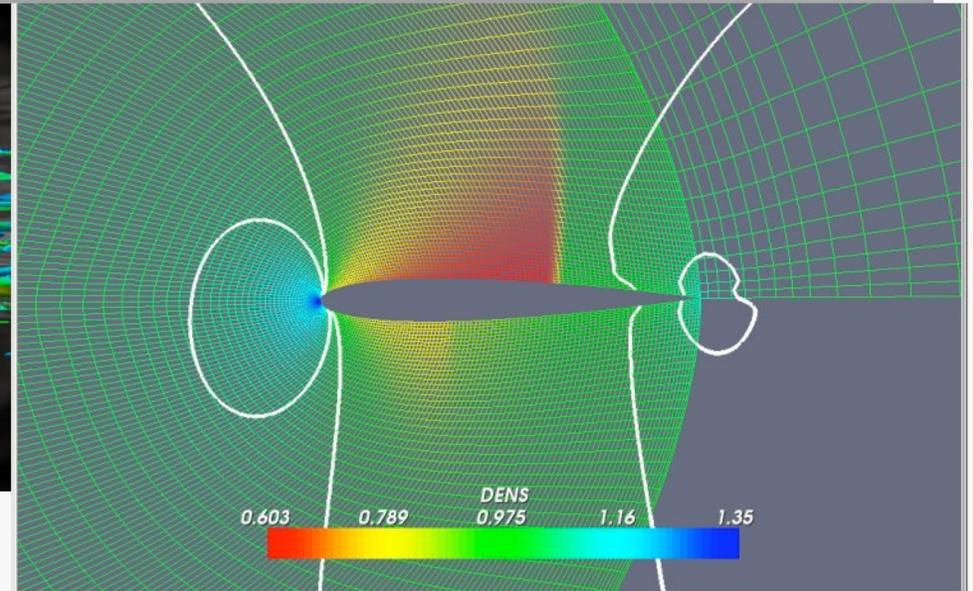
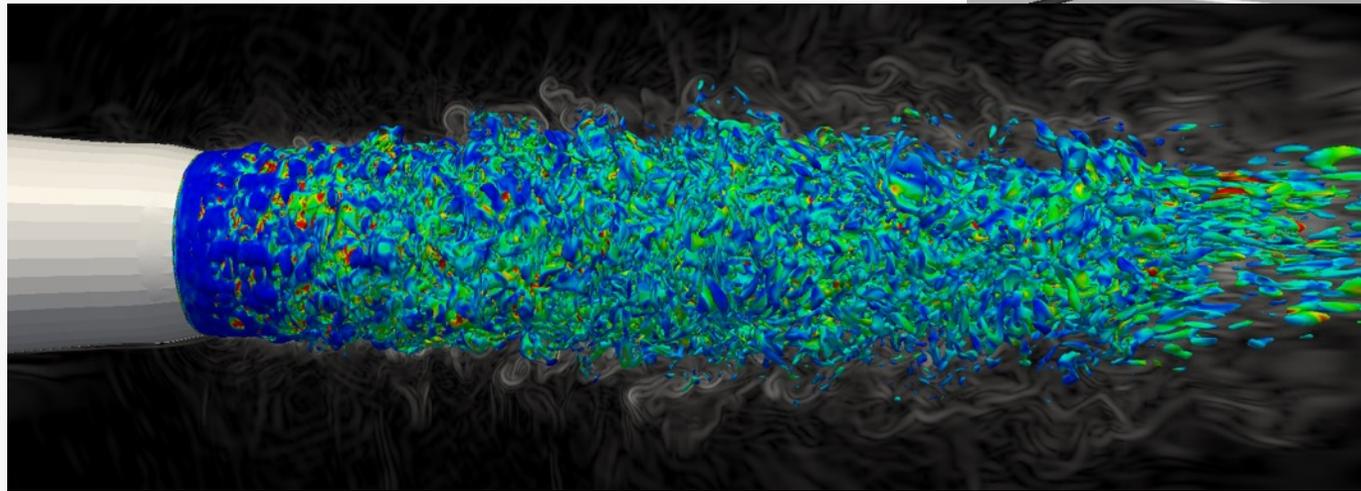
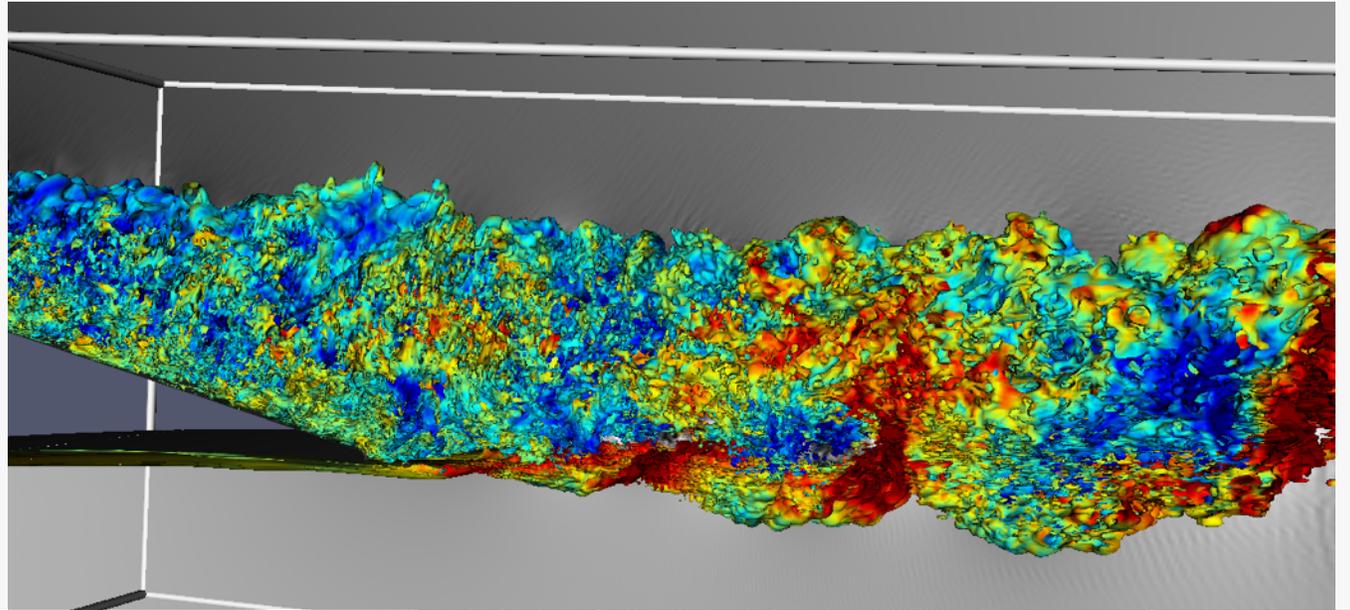
A Line (2D) or Surface (3D),
representing a constant value

VisIt & ParaView:

– good at this

vtk:

– same, but again requires more effort



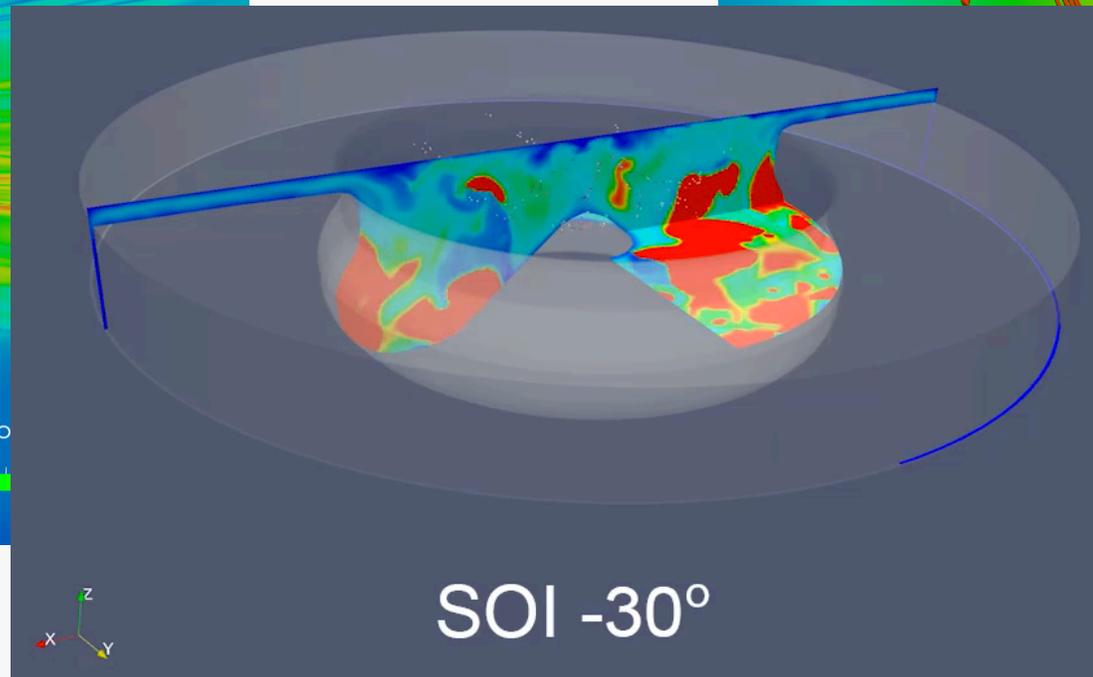
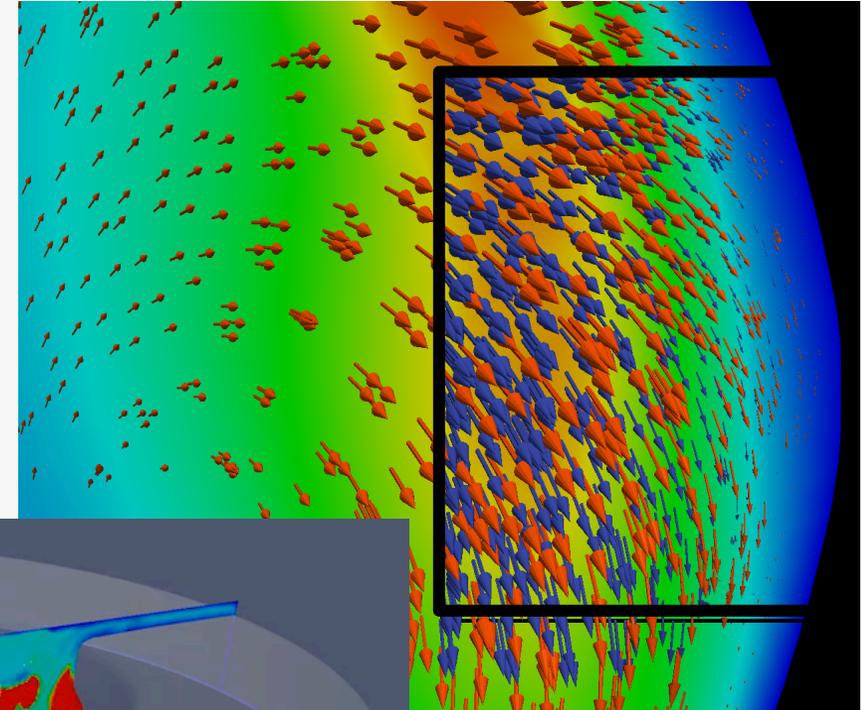
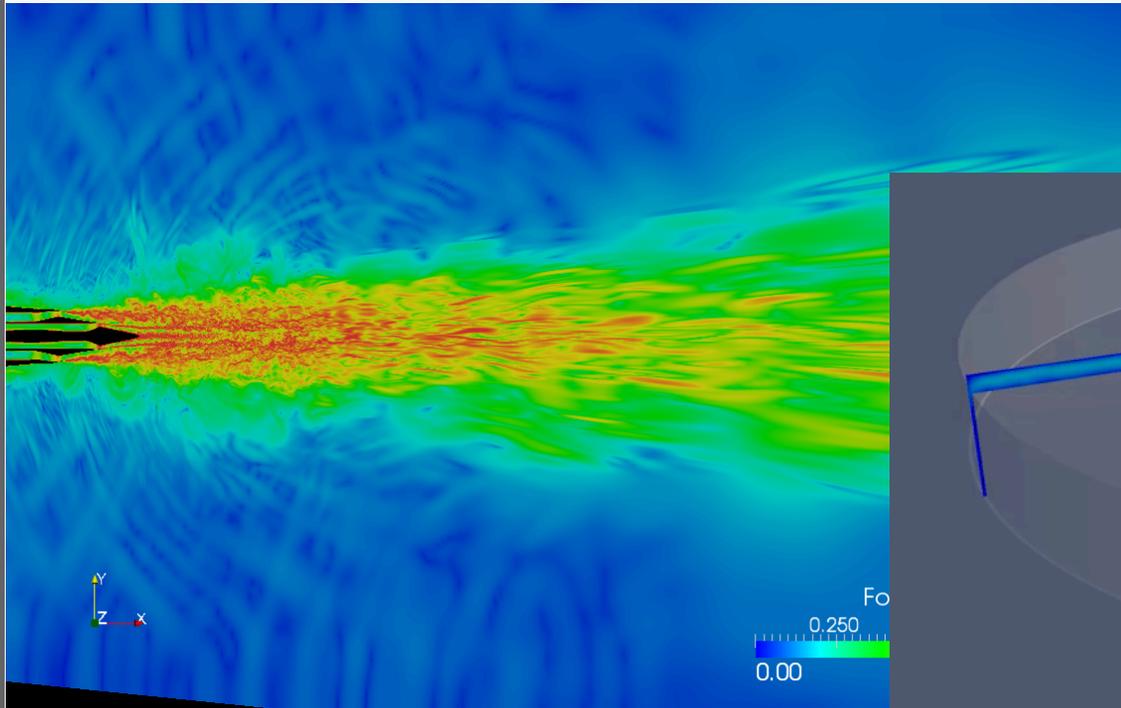
Data Representations: Cutting Planes

Slice a plane through the data

– Can apply additional visualization methods to resulting plane

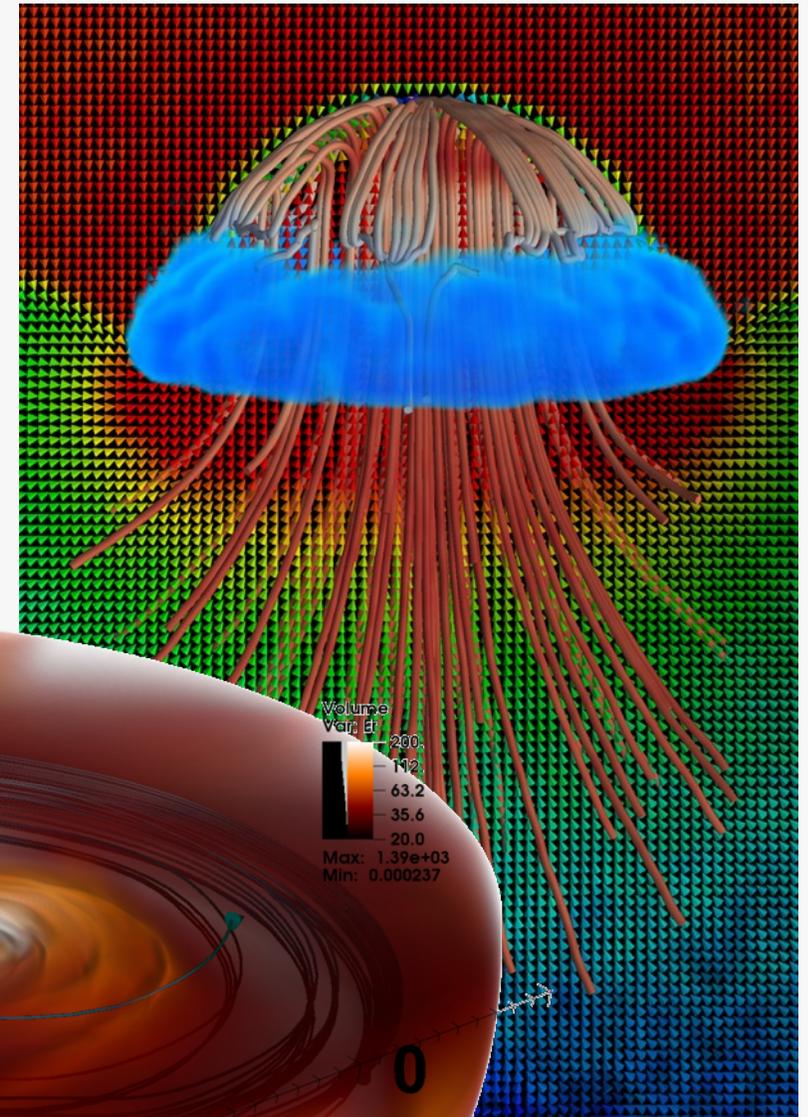
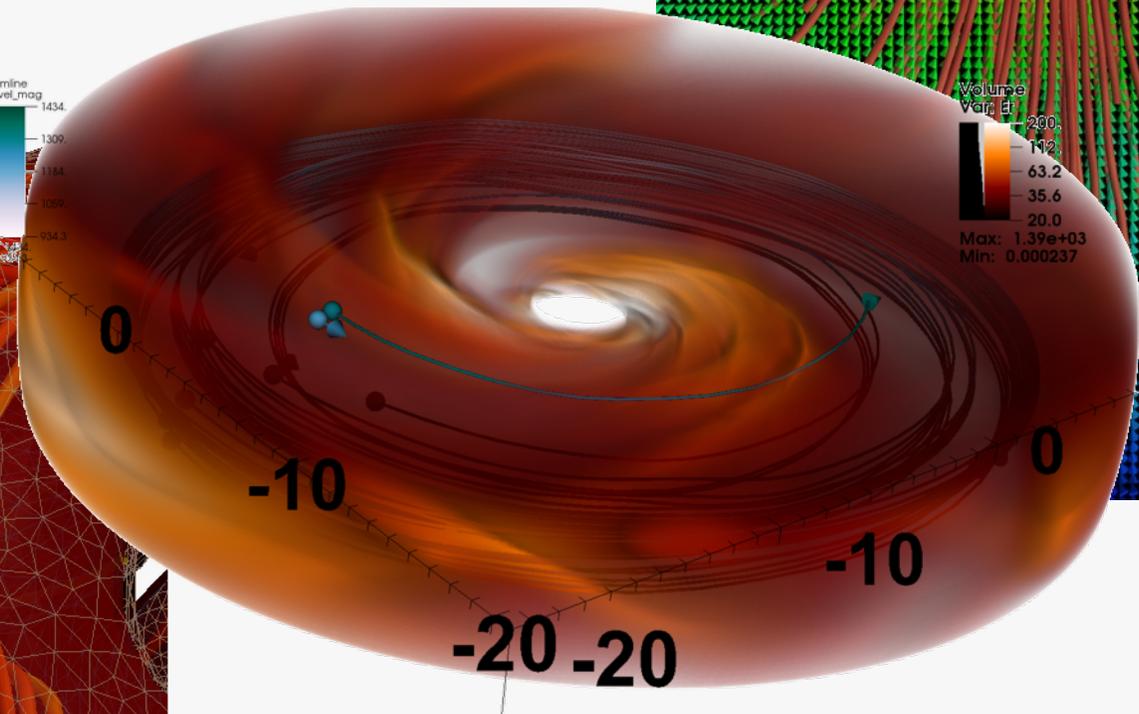
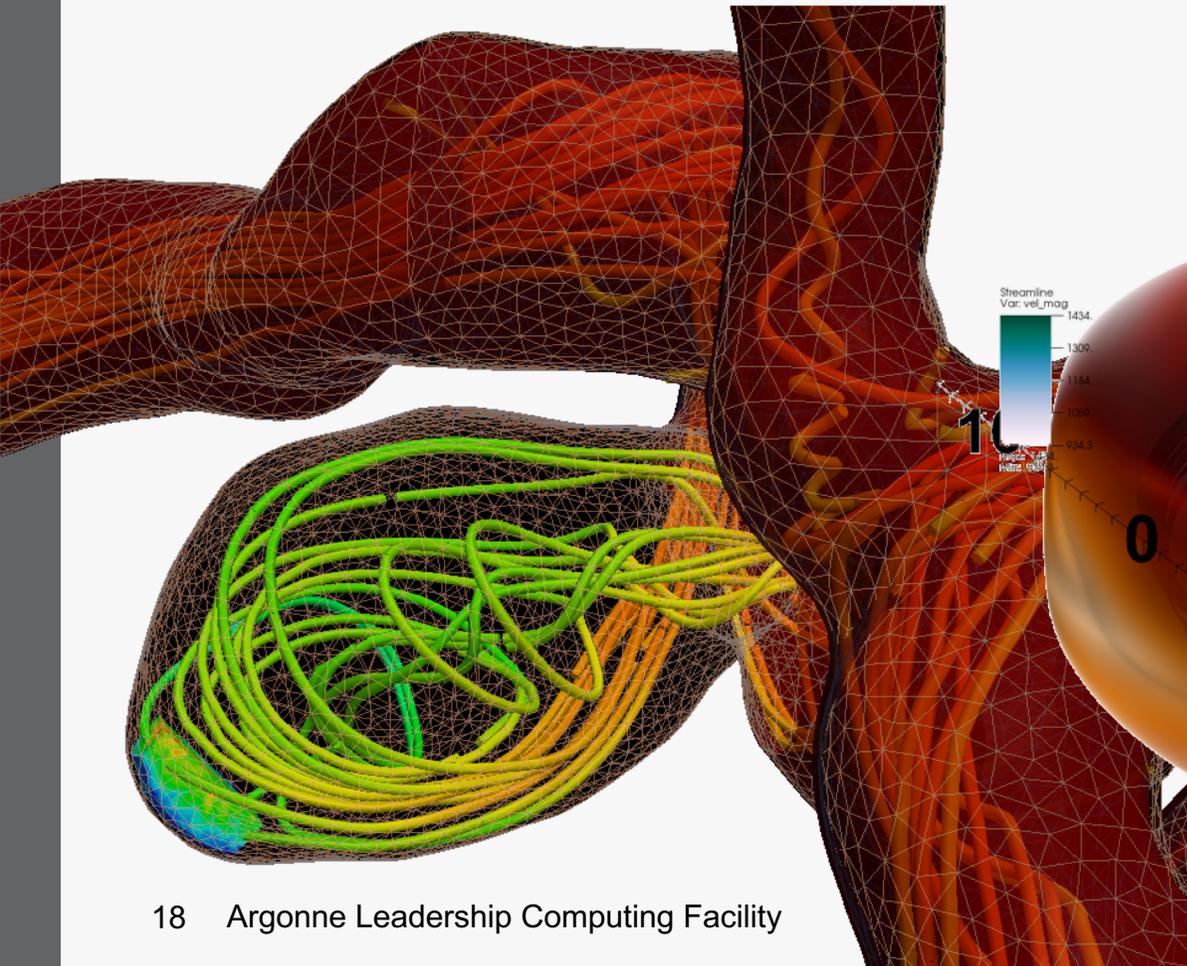
Visit & ParaView & vtk good at this

VMD has similar capabilities for some data formats



Data Representations: Streamlines

From vector field on a mesh (needs connectivity)
– Show the direction an element will travel in at any point in time.
Visit [ParaView](#) & [vtk](#) good at this



Data Representations: Pathlines

From vector field on a mesh (needs connectivity)

– Trace the path an element will travel over time.

Visit & ParaView & vtk good at this



Molecular Dynamics Visualization

VMD:

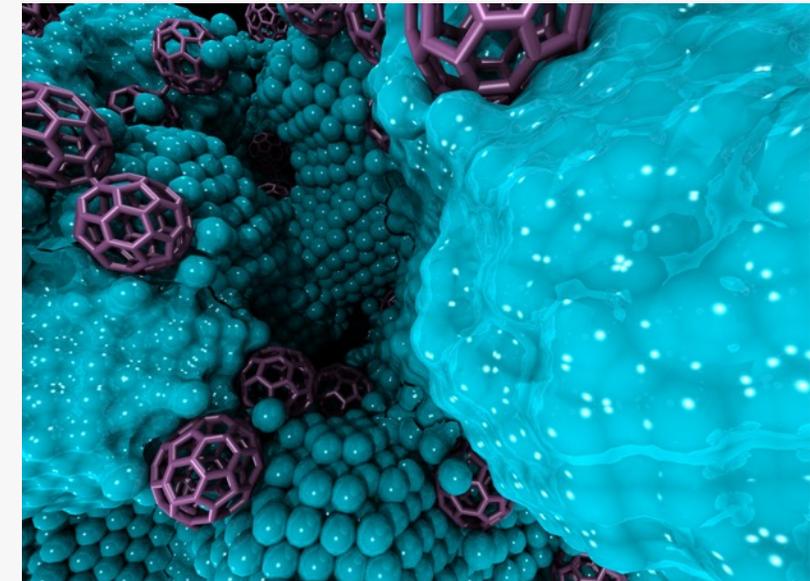
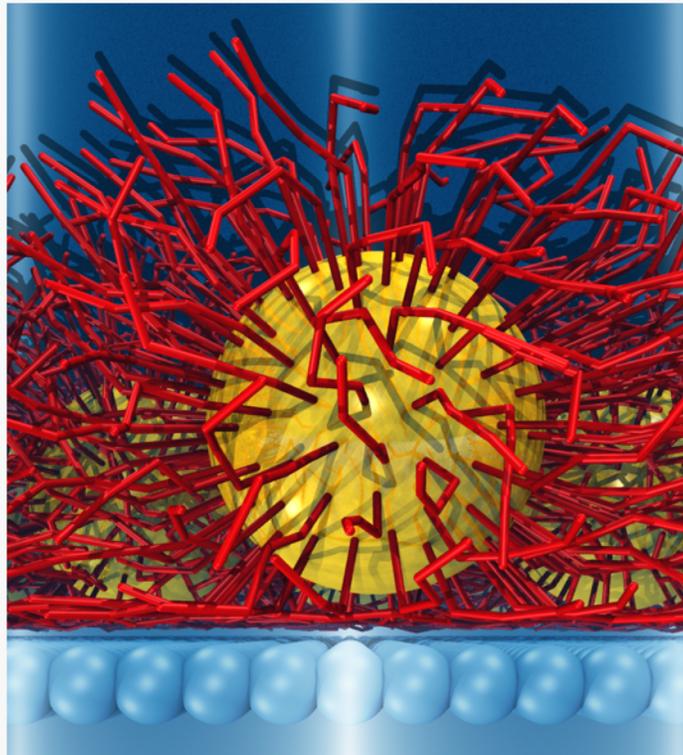
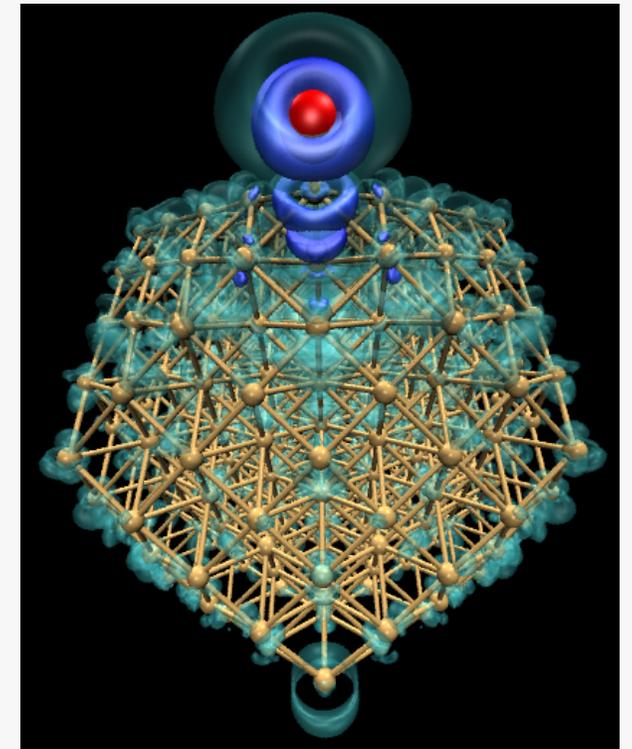
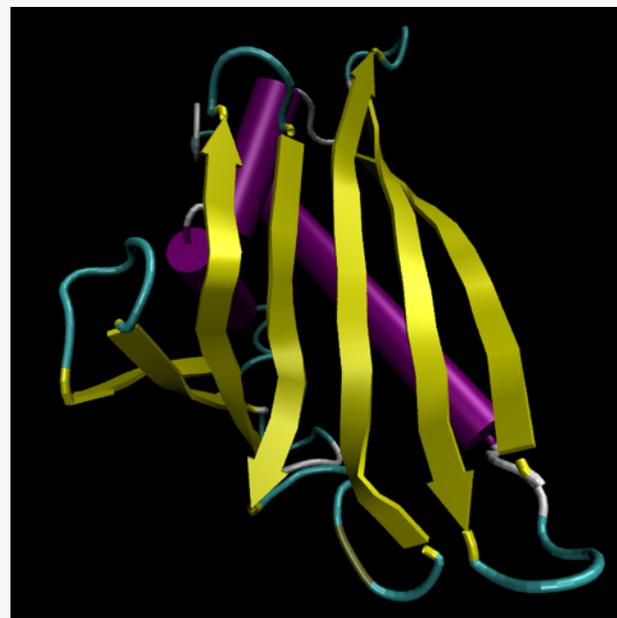
- Lots of domain-specific representations
- Many different file formats
- Animation
- Scriptable

VisIt & ParaView:

- Limited support for these types of representations, but improving

VTK:

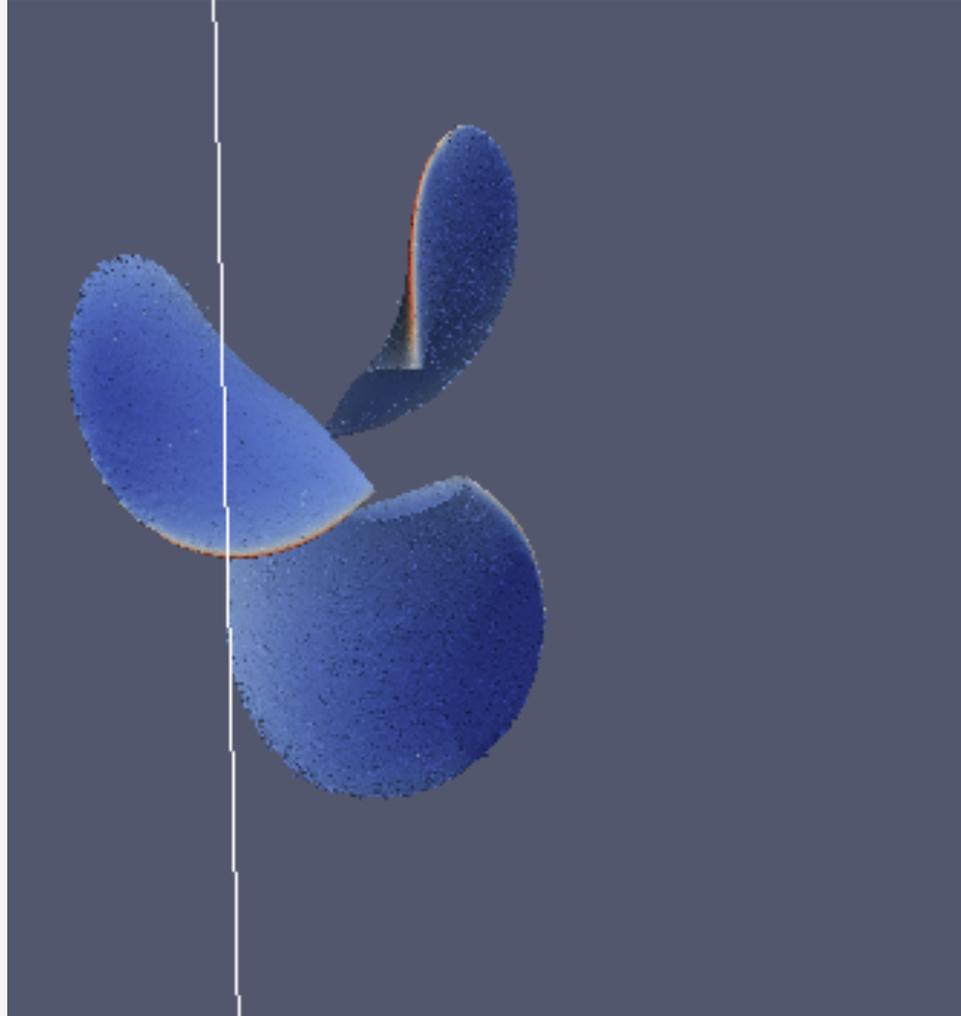
- Anything's possible if you try hard enough



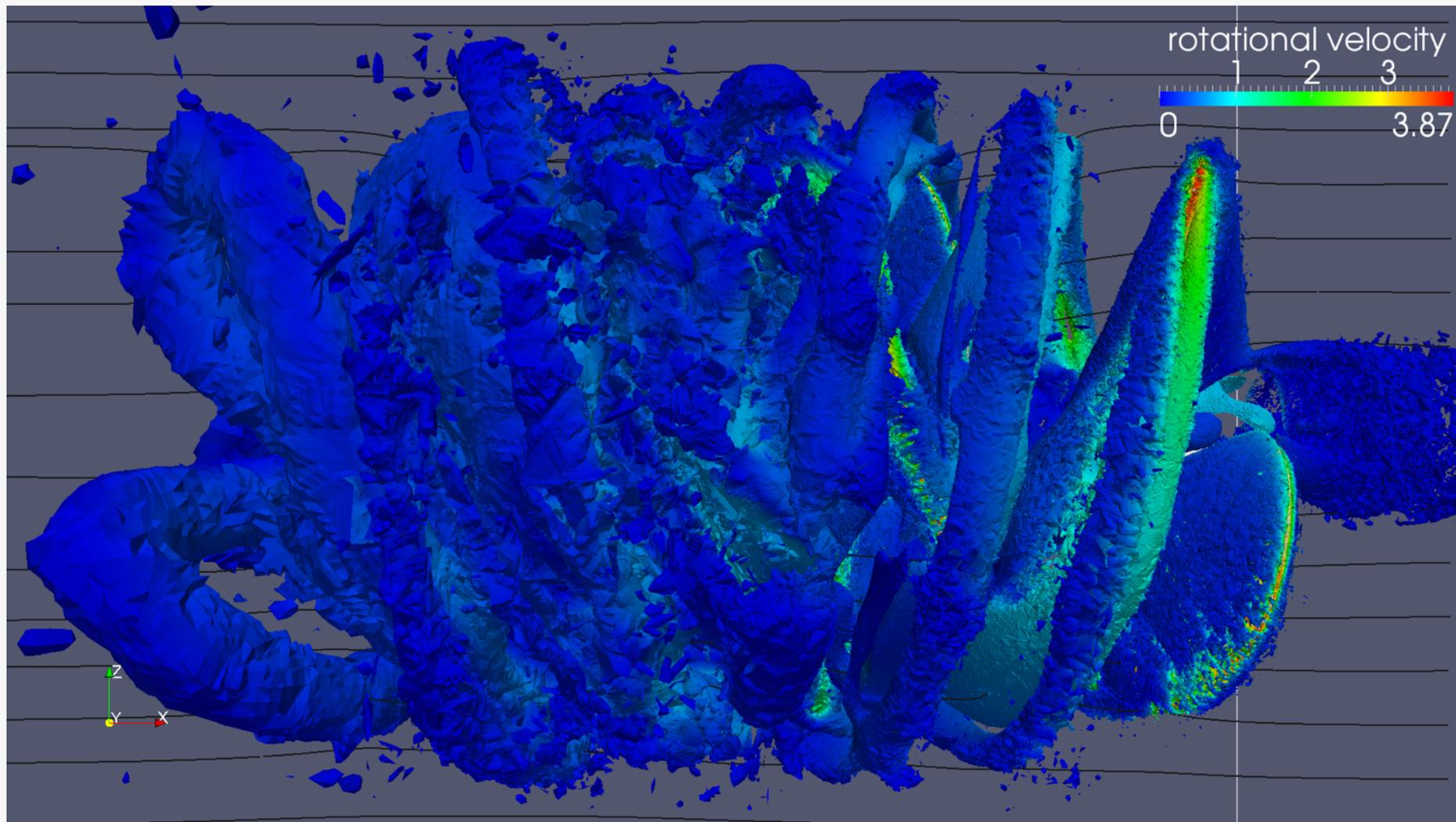
Visualization for Debugging



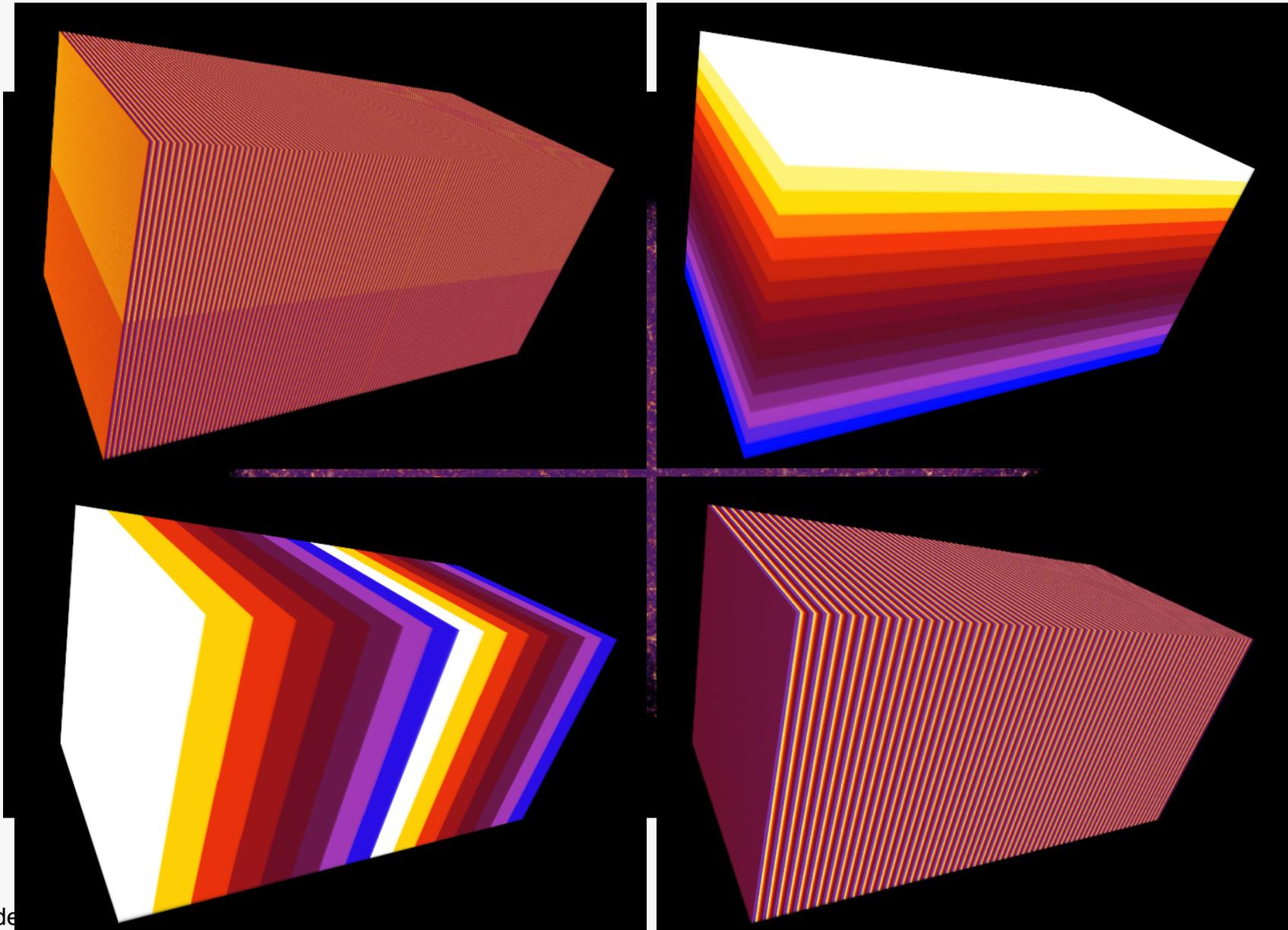
Visualization for Debugging



Visualization for Debugging

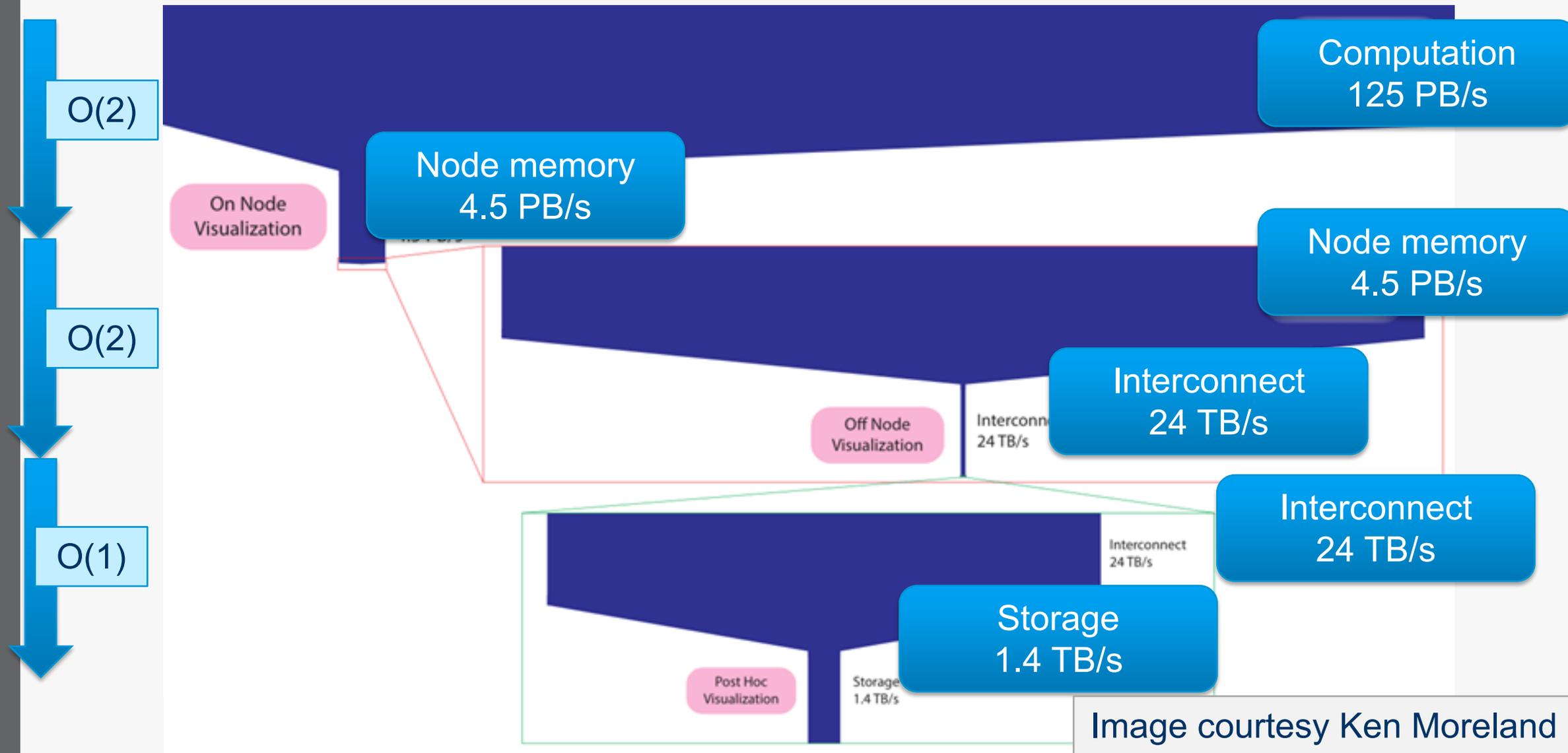


Visualization as Diagnostics: Color by Thread ID



In Situ Visualization and Analysis

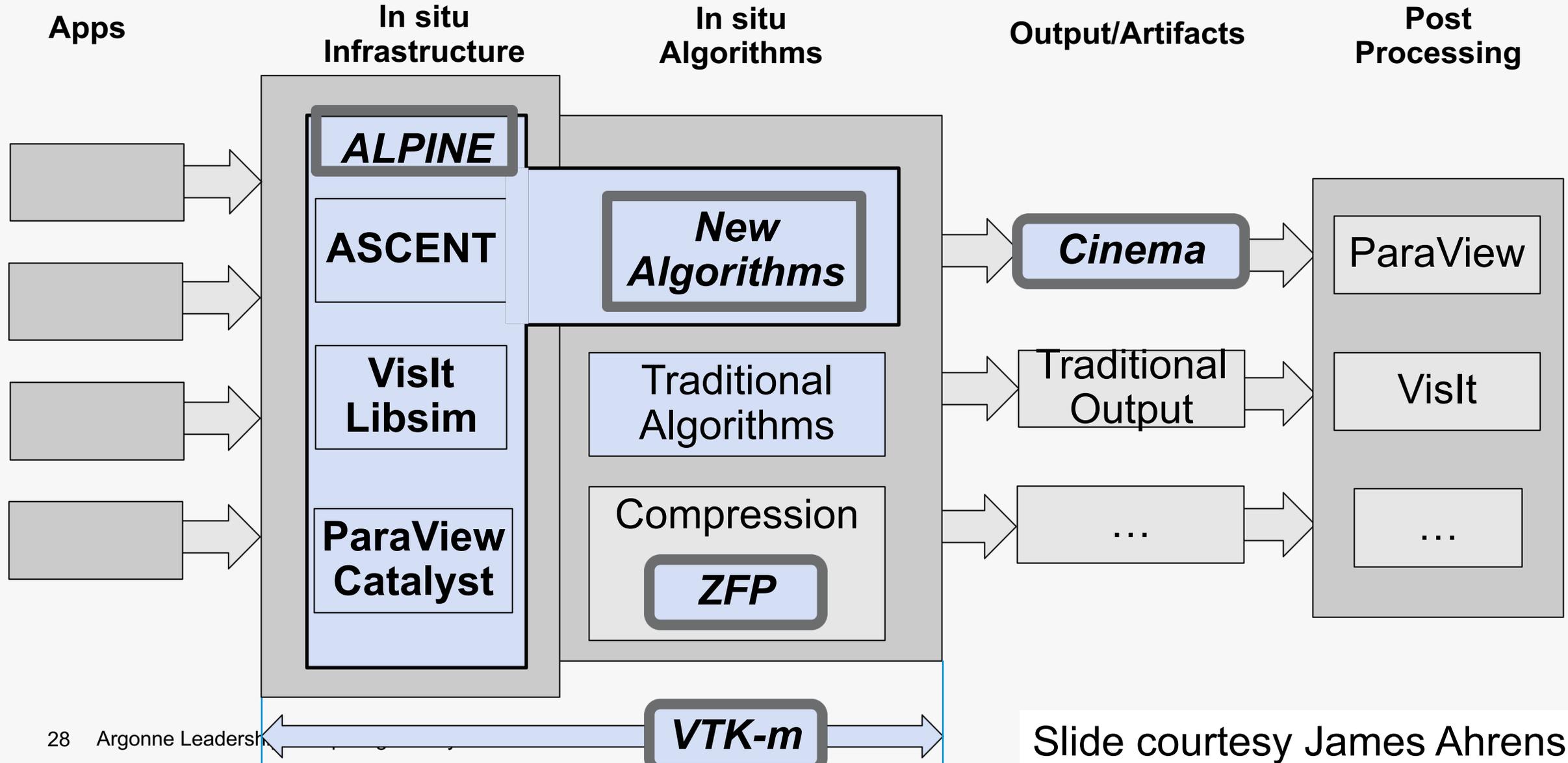
Five orders of magnitude between compute and I/O capacity on Titan Cray system at ORNL



What are the problems?

- Not enough I/O capacity on current HPC systems, and the trend is getting worse.
- If there's not enough I/O, you can't write data to storage, so you can't analyze it: lost science.
- Energy consumption: it costs a lot of power to write data to disk.
- Opportunity for doing better science (analysis) when have access to full spatiotemporal resolution data.

ECP Software Technology Data and Visualization projects provide an integrated workflow



Cinema

Approach: Visualize all results needed while simulation data is in memory

- Operators, camera positions/angles, simulation and algorithmic parameters

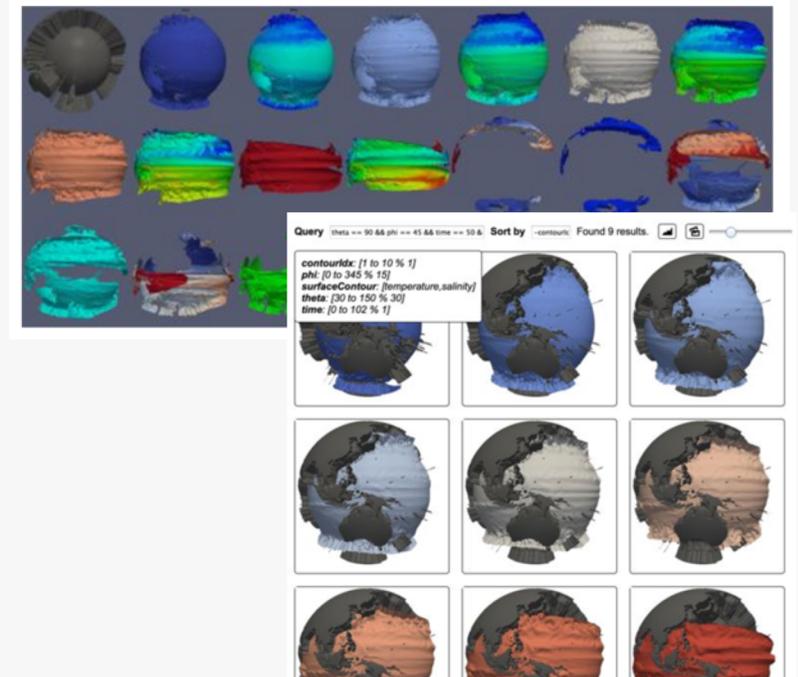
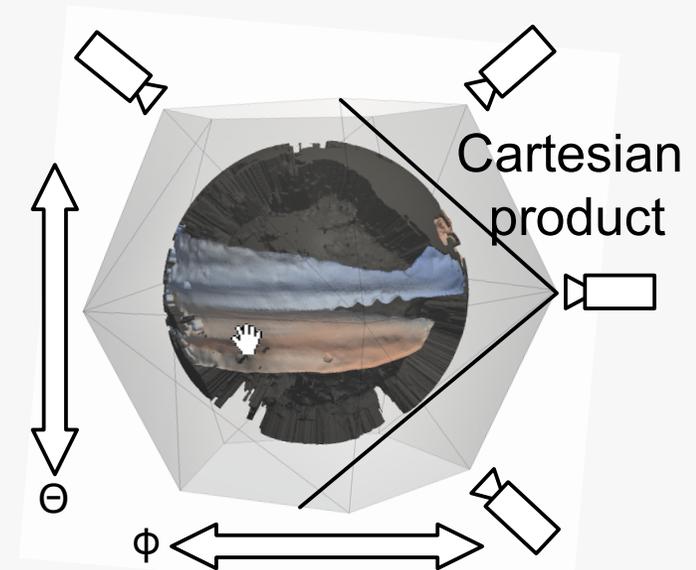
Result: Database of images

- Pixel accurate results when compared to post-processing rendering of the same data

Properties of this solution:

- Sampling of visualization result image output space
- Visualization/rendering as sampling/data reduction operator
- Note we can evaluate and optimize this finite set of image outputs

Cinemascience.org



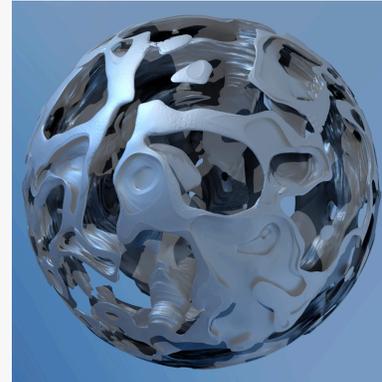
VTK-m Delivering Portable Performance of Visualization Algorithms Across ECP Processors

Development is accelerated by VTK-m's write once, run everywhere

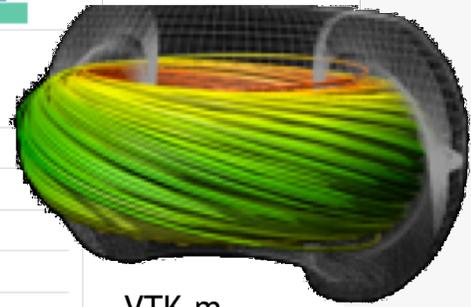
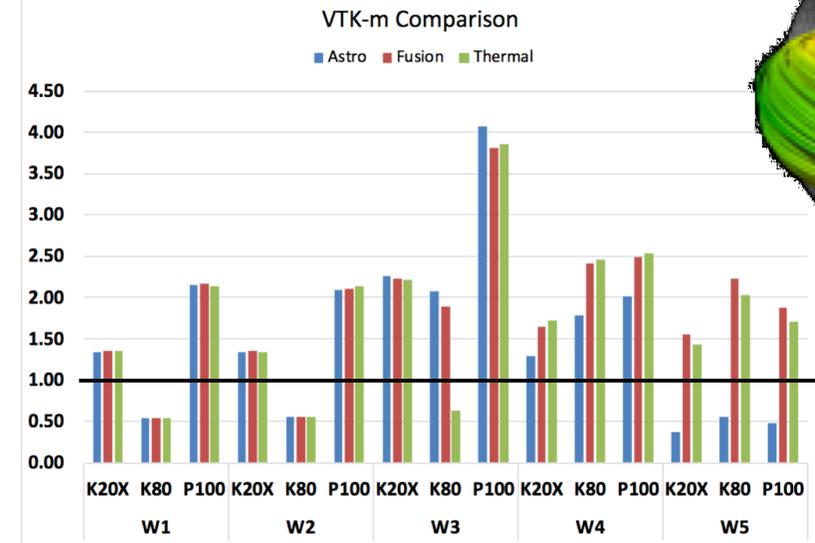
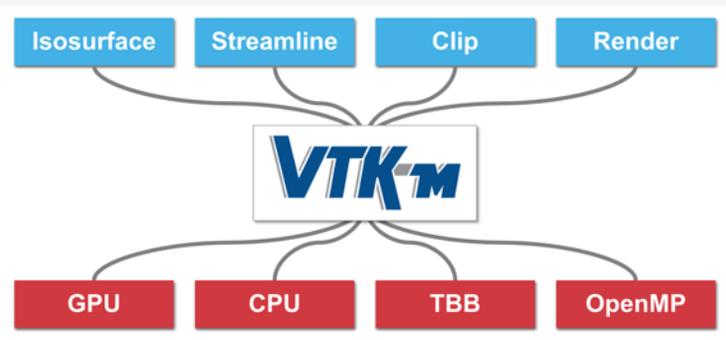
- Data parallel programming abstraction

Ray tracing performance in VTK-m is within a factor of 2 of highly optimized, processor-specific implementations developed by Intel and NVIDIA [Moreland, et al., 2016]

Particle advection in VTK-m performs *better* than code specifically developed for CUDA processors [Pugmire, et al. 2018]



| Dataset | Algorithm | Millions of rays per second | Dataset | Algorithm | Millions of rays per second |
|---------|-------------|-----------------------------|---------|-----------|-----------------------------|
| LT_350K | OptiX Prime | 357.6 | LT_350K | Embree | 51.9 |
| | EAVL | 150.8 | | EAVL | 27.7 |
| | VTK-m | 164.5 | | VTK-m | 38.5 |
| LT_372K | OptiX Prime | 322.4 | LT_372K | Embree | 56.5 |
| | EAVL | 124.7 | | EAVL | 26.1 |
| | VTK-m | 140.8 | | VTK-m | 36.0 |
| RM_350K | OptiX Prime | 436.5 | RM_350K | Embree | 64.8 |
| | EAVL | 197.5 | | EAVL | 33.3 |
| | VTK-m | 200.8 | | VTK-m | 47.8 |
| RM_650K | OptiX Prime | 420.4 | RM_650K | Embree | 65.9 |
| | EAVL | 172.9 | | EAVL | 35.6 |
| | VTK-m | 166.0 | | VTK-m | 49.1 |
| RM_970K | OptiX Prime | 347.1 | RM_970K | Embree | 59.1 |
| | EAVL | 152.8 | | EAVL | 29.3 |
| | VTK-m | 163.5 | | VTK-m | 41.0 |
| RM_1.7M | OptiX Prime | 266.8 | RM_1.7M | Embree | 52.4 |
| | EAVL | 136.6 | | EAVL | 27.0 |
| | VTK-m | 148.8 | | VTK-m | 37.8 |
| RM_3.2M | OptiX Prime | 264.5 | RM_3.2M | Embree | 48.4 |
| | EAVL | 124.8 | | EAVL | 28.3 |
| | VTK-m | 134.5 | | VTK-m | 33.9 |
| Seismic | OptiX Prime | 267.8 | Seismic | Embree | 43.2 |
| | EAVL | 106.3 | | EAVL | 25.2 |
| | VTK-m | 119.4 | | VTK-m | 34.5 |



VTK-m faster

Slide courtesy James Ahrens and the VTK-m team



Two Frameworks for In Situ Vis and Analysis at ALCF



- “Write once, run everywhere” design
 - Data model based on VTK from Kitware
 - Supports a variety of backends, including ParaView/Catalyst, VisIt/LibSim, ADIOS, Python
- Flyweight design, minimizes dependencies
 - Data model based on Conduit from LLNL
 - Vis and analysis algorithms implemented in VTK-m

Instrumenting Simulation Codes



```
1. initialize sim
2. if do_insitu bridge::initialize
3. do
4.   compute new state
5.   if do_io write plot file
6.   if do_insitu bridge::execute
7. while !done
8. if do_insitu bridge::finalize
9. finalize sim
```

```
// |
// Run Ascent
//
Ascent ascent;
ascent.open();
ascent.publish(data);
ascent.execute(actions);
ascent.close();
```

SENSEI + ASCENT tutorial at SC19

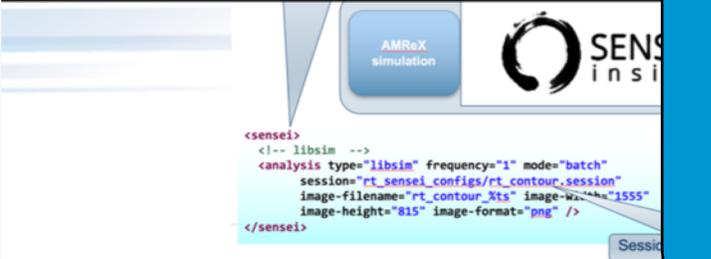
Slides and Virtual Machine available here:

<https://sensei-insitu.org/tutorials/sc19.html>

In Situ Analysis and Visualization with



and



```
<sensei>
  <!-- libsim -->
  <analysis type="libsim" frequency="1" mode="batch"
    session="rt_sensei_configs/rt_contour_session"
    image-filenames="rt_contour_*.x" image-width="1555"
    image-height="815" image-format="png" />
</sensei>
```

SENSEI + ASCENT
tutorial at SC20
Details TBA

Additional Resources

Visualization Help for ALCF users

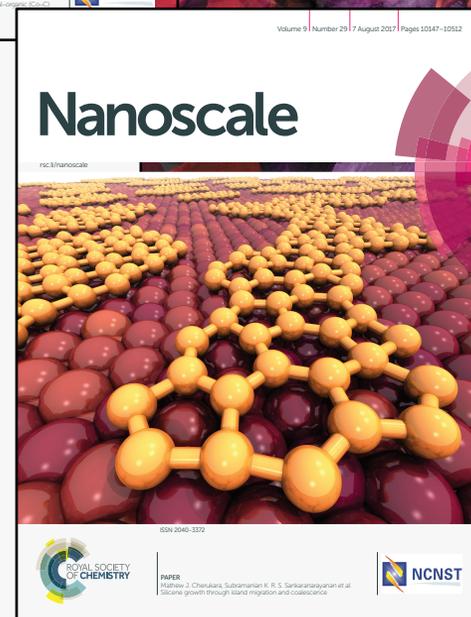
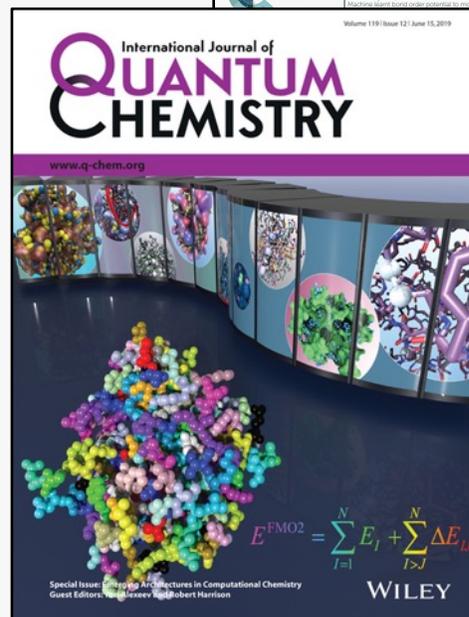
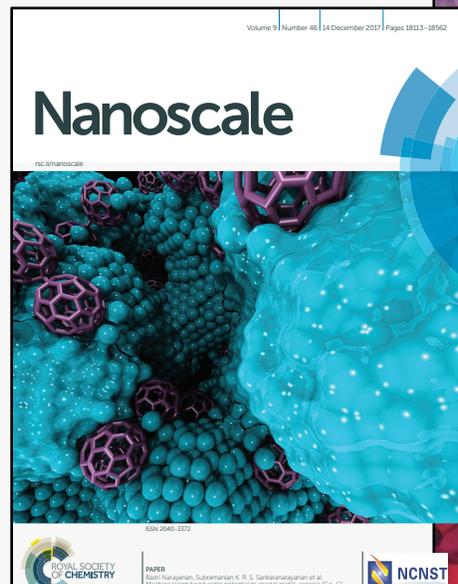
support@alcf.anl.gov

Publication Images & Covers

Animations

- SC Visualization Showcase [Best Vis Finalist 2014-2019]
- APS Division of Fluid Dynamics Gallery of Fluid Motion
- SC Gordon Bell Submissions
- Press Releases

InSitu Vis and Analysis



In situ additional resources



- Project page
<https://sensei-insitu.org/>
- Repository
<https://gitlab.kitware.com/sensei/sensei>

- Website + Docs:
<http://ascent-dav.org>
- Repository:
<https://github.com/Alpine-DAV/ascent>

2019 ASCR Workshop on In Situ Data Management

- **Pervasive ISDM:** Apply ISDM methodologies and in situ workflows at a variety of platforms and scales.
- **Co-designed ISDM:** Coordinate the development of ISDM with the underlying system software so that it is part of the software stack.
- **In Situ Algorithms:** Redesign data analysis algorithms for the in situ paradigm.
- **Controllable ISDM:** Understand the design space of autonomous decision-making and control of in situ workflows.
- **Composable ISDM:** Develop interoperable ISDM components and capabilities for an agile and sustainable programming paradigm.
- **Transparent ISDM:** Increase confidence in reproducible science, deliver repeatable performance, and discover new data features through the provenance of ISDM.

<https://www.osti.gov/servlets/purl/1493245>



QUESTIONS?

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